# 2.1.6 SYMBOLS

We shall generally write state variables in lowercase (except the temperature in Kelvin and pressure) and intensive state functions (referred to the mass unit), and capitalize the extensive quantities (referred to the total mass).

Following established practice, however, an exception will be made for the kinetic energy K, the work of external forces W and the heat exchanged with the outside Q, which is written in capitals, even if expressed in mass units, and for the useful work  $\tau$ , which is always written in lowercase.

We pass from one to another by multiplying the first by the mass m (for closed systems), or the mass flow  $\dot{m}$  (for open systems).

volume  $v = \frac{V}{m} = \frac{\dot{V}}{\dot{m}} (m^3 \text{ kg}^{-1})$  internal energy  $u = \frac{U}{m} = \frac{\dot{U}}{\dot{m}} (J \text{ kg}^{-1})$ 

entropy 
$$s = \frac{S}{m} = \frac{\dot{S}}{\dot{m}}$$
 (J kg<sup>-1</sup> K<sup>-1</sup>) enthalpy  $h = \frac{H}{m} = \frac{\dot{H}}{\dot{m}}$  (J kg<sup>-1</sup>)

For convenience, we will refer, whenever possible, to the unit mass of fluid.

In this book, as we will use extensive quantities only very rarely, to avoid burdening the notation, we take the liberty to also use capital letters for the molar quantities, which we sometimes use. When this is the case, we will say so.

Remember also that the kilomol (1 kmol) is the amount of a substance whose mass is equal to its molar mass M in kilograms: 1 kmol of  $O_2$  has a mass of 32 kg.

If M\* is the mass of a molecule, M\* =  $\frac{M}{N_0}$ , N<sub>0</sub> being the Avogadro number:

 $N_0 = 6 \ 10^{23}$  molecules/g.

In the normal state (0 °C, 1 bar), the volume occupied by 1 kmol is equal to 22.414  $m^3$ .

### 2.2 Energy exchanges in a process

Thermal machine components are traversed by fluids that are most often gaseous or liquid. Over the processes that they undergo, these fluids exchange energy with the outside or between themselves in two forms: mechanical, traditionally denoted W, and thermal, denoted Q. Given their practical importance, we will first study the energy exchanges.

Consistent with our bias to favor as simple as possible a presentation of the thermodynamics fundamentals, we limit ourselves in what follows to steady state systems, because even if the results we establish generalize quite easily, it is necessary to adopt a heavier formalism if we want to be rigorous.

## 2.2.1 WORK &W OF EXTERNAL FORCES ON A CLOSED SYSTEM

Consider a closed system phase. External forces acting on it are usually limited on the one hand in the action of gravity on the fluid mass, and on the other hand of pressure on its boundaries.

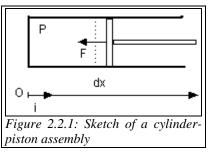
In heat engines, the work of gravity is in most cases negligible compared to that of actions called "contact". To fix these ideas, the work provided by a mass of 1 kg of

water falling from a height of 100 m is equal to 980 J, while that of the same mass of steam at 500 °C isentropically expanded from 100 bar to 1 bar is equal to 983 kJ, or 1000 times greater.

Consequently, in thermal machines, the work of mass forces will most often be negligible compared to that of pressure.

Consider a fluid at rest (Figure 2.2.1), at uniform pressure P enclosed in a cylinder whose walls are all fixed except a piston capable of moving in one direction. Now exert a force  $\vec{F}$  on the piston to move it slowly enough (so that at any time the system can be likened to a phase).

Let us consider an axis (O,  $\vec{i}$ ) directed from the bottom of the cylinder (x=0  $\Rightarrow$  V=0). The force being exerted by the system outside,  $\vec{F} = - ||\vec{F}||$ 



Call A the piston section, and  $\vec{dx} = dx \vec{i}$  its motion.

Obviously ||F|| = P A, and work m  $\delta W_A$  received by the mass m of fluid is:

$$m \delta W_A = \vec{F} \cdot d\vec{x} = - ||F|| dx \vec{i} \cdot \vec{i} = -PA dx = -P dV.$$

dV being the volume change of the mass, equal to mdv, and:

$$\delta W_{\rm A} = - \, {\rm Pdv} \tag{2.2.1}$$

In case of compression, the volume change is negative and the work received is positive. We note this work with index A, to indicate it is exercised on the surface of the system considered.

This expression, which generalizes easily to a closed system of any form, is valid only if the system remains in static equilibrium, i.e. if the following assumptions are true:

the pressure remains uniform across the system;

the fluid remains at rest.

Note that formula (2.2.1) implies that the work received by the system is positive, and that the work it provides is negative. By convention, we generalize this result by counting positively the energy received by a system, and negatively the energy it provides to the outside.

During a reversible process making a closed phase pass from state 1 to state 2, the mass work of contact actions has the value:

$$W_{A} = -\int_{1}^{2} P dv$$
 (2.2.2)

In case the gravity work is not negligible, one can easily show that it is expressed as:

 $dW_v = -g dz \tag{2.2.3}$ 

g > 0 is the acceleration of gravity, and z the altitude of the point, counted positively upwards. We note such work with index v, to indicate it is exercised in the volume of the system considered.

We have then:

 $\mathbf{W} = \mathbf{W}_A + \mathbf{W}_v$ 

2.2.2 HEAT TRANSFER

Consider a simple fluid mass, within which no friction occurs.  $\delta Q$  is the quantity of heat exchanged with the outside and received by the unit of fluid mass in an infinitely small process.

An important experimental fact, the basis of compressible fluid thermodynamics, is that  $\delta Q$  is a differential form of the fluid mass state, called a calorimetric equation.

For example, in the case of a mono-variant system (equilibrium between phases during a change of state), the calorimetric equation depends only on the quality x, ratio of vapor mass to total mass (liquid + vapor) in the case of vaporization or condensation:  $\delta Q = L dx$ 

L is the change of state enthalpy.

More generally, the calorimetric equation that connects  $\delta Q$  to the simple fluid (bivariant) state variables can take three well known equivalent canonical forms:

$$\begin{split} \delta Q &= c_p \ dT + h \ dP \\ \delta Q &= c_v \ dT + l \ dv \end{split} \tag{2.2.5} \\ \delta Q &= \mu \ dP + \lambda \ dv \end{split}$$

Coefficients  $c_p$ ,  $c_v$ , h, l,  $\mu$  et  $\lambda$  are called equilibrium fluid calorimetric coefficients (note that h is **not** enthalpy, which will be introduced later). They are linked by differential relations that can be obtained without significant difficulty, but which do not interest us. Just know that the calorimetric properties of a fluid are determined by knowing two of these six coefficients.

Subsequently, we will use only coefficients  $c_p$  and  $c_v$ , which are respectively called specific heat capacity at constant pressure, and specific heat capacity at constant volume, whose former name was "specific heat".

For a solid or a liquid,  $c_p \approx c_v$ , and  $\delta Q \approx c dT$ 

For an ideal gas, depending on whether we are dealing with an open system operating at constant pressure, or a closed one operating at constant volume,  $\delta Q = c_p dT$  or  $\delta Q = c_v dT$ . For a real gas, use one of the canonical forms above.

The above equations are however valid only if certain conditions are met:

Firstly, the mass of fluid must be completely homogeneous, i.e. comparable to a phase;

Secondly, we assumed that there was no irreversibility inside or at the boundary of the fluid mass. If any, the relationship becomes:

(2.2.4)

Thermodynamics fundamentals

 $\delta Q < c_p dT + h dP \qquad \text{We will then write:}$  $\delta Q = c_p dT + h dP - \delta \pi \qquad (2.2.6)$ 

 $\delta\pi$ , essentially a positive term, has a very simple physical meaning: it is the heat generated by mechanical friction within the fluid. Although it differs profoundly, it produces the same effect as heat received from the outside. Its meaning will be clarified during the presentation of the second law of thermodynamics (Section 2.4).

By convention, therefore, we denote  $\delta Q$  the heat exchanged with the outside, and counted positively if received by the system, and  $\delta \pi$  the heat dissipated by internal friction if any. In practice, it is important to distinguish these two forms of heat, otherwise serious reasoning errors can be made. In particular, the processes without heat exchange with the outside, called adiabatic, are such that  $\delta Q = 0$ , whether or not the seat of irreversibility, that is to say  $\delta \pi$  being either zero or not.

### 2.3 FIRST LAW OF THERMODYNAMICS

Now that we have established expressions for calculating the mechanical and thermal energy exchange of a fluid mass with its surroundings, we can recall the first law of thermodynamics. As usual, we start with the expression for closed systems, well known to all, and we generalize for open systems.

The first principle, also known as the equivalence principle or the energy conservation principle, says that the energy contained in an isolated system or evolving in a closed cycle, remains constant, whatever the processes it undergoes. The various forms that can take the energy of a system: mechanical energy, heat energy, potential energy, kinetic energy etc. are all equivalent to each other under the first principle.

## 2.3.1 DEFINITION OF INTERNAL ENERGY U (CLOSED SYSTEM)

Any closed physical system is characterized by a scalar U, based exclusively on state variables, and such that for any real process:

$$\Delta U + \Delta K = W + Q$$

(2.3.1)

K being the kinetic energy of the system, W the work of external forces, expressed for the total mass of the system and given by relation (2.3.4)  $W = W_A + W_v$ , and Q the heat exchanged by the system with outside for the process considered.

U is an extensive quantity called the internal energy of the system, U + K is sometimes called the system total energy. For a phase of mass m, U = m u, u being the specific internal energy.

Let us recall that the state variables that define, in the most general case, a physical system, fall into four broad categories:

- mechanical variables, position or deformation;
- temperature;
- chemical variables;
- electric variables.

Only the first two will be considered in most applications we have to deal with, and the third will be used for fluid mixtures and combustion reactions. As for the fourth,

25